











consumed for performing the bi-axial tracking:  $E_C = 67.08$  Wh/day. The supplementary energy obtained by tracking the sun path is obtained in the following way:  $\varepsilon = E_{PT} - (E_{PF} + E_C) = 13863.88 - (10305.65 + 67.08) = 3491.15$  Wh/day, representing an effective energy gain (reported to the fixed PV system) of 33.87%. Such computations were performed for all intervals during the year, the average annual energy gain being of 38.71%, thus justifying the use of the proposed dual-axis azimuthal tracking mechanism.

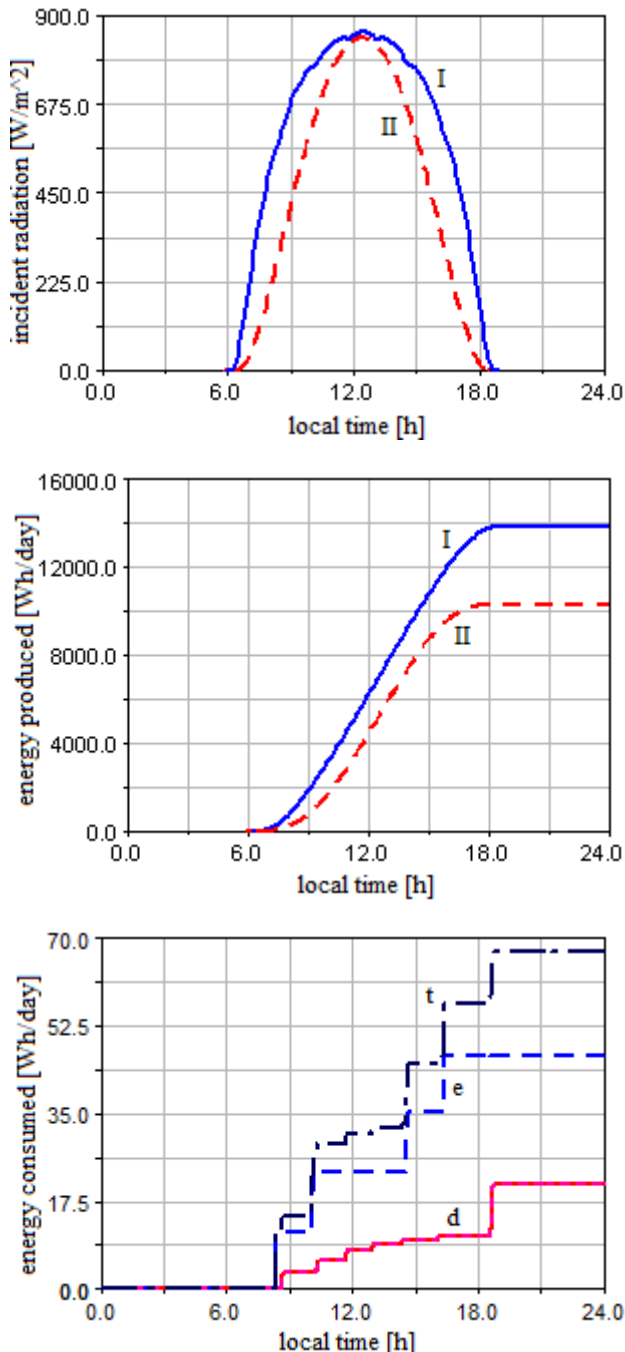


Fig. 7. Results of the simulation in a virtual prototyping environment for the spring equinox day.

#### 4. Conclusions

The application presented in this paper is an edifying example of the possibilities offered by virtual prototyping in the optimal design of PV tracking systems. The

proposed dual-axis solar tracker has several important advantages, such as the ability to orient medium and large PV platforms, reducing the cost by minimizing the number of motor sources relative to the classical solution of individual modules, ensuring very good tracking accuracy while proving high stability and robustness performance. By the way in which the proposed dual-axis solar tracker is designed, the energy gain (by reference to the equivalent fixed system) is maintained to values that prove its usefulness/viability.

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